

# A Short Tutorial on Matlab

( by T. Co, ©2003,2004 )

## Part I. BASICS

### I. Assigning Values to Variables, Vectors and Matrices

- Use the equality symbol, e.g. **A=3**
- Variables are case sensitive: **temperature** is not the same as **Temperature**
- To check values, just type the variable name
- There are special constants already available, e.g. **pi**, **Inf**
- For complex numbers, either use **3+2i** or **3+2j**
- Vectors and matrices are enclosed with square brackets:
  - a) Elements of rows are separated by commas: **A=[1,2,3]**
  - b) Elements of columns are separated by semicolons: **B=[1;2;3]**
  - c) Matrices can be seen as columns of row vectors, **C=[1,2,3;4,5,6]**
- Alternatively, use spaces to separate row elements and return keys for column elements:  
**B = [ 1 2 3  
4 5 6  
1 0 1]**
- To get size information,
  - a) **size(A)** yields [# rows, # cols]
  - b) **size(A,1)** yields # rows
  - c) **size(A,2)** yields # cols
  - d) **length(v)** yields # elements in vector v
- Some shortcuts are available:
  - a) **A = 1:0.1:2** yields a row vector [1, 1.1, 1.2, ... , 1.9, 2]
  - b) **diag([1,2,3])** yields a diagonal matrix [1,0,0 ; 0,2,0 ; 0,0,3]
  - c) **diag([1,2,3],1)** yields a matrix  
[ 0,1,0,0 ; 0,0,2,0 ; 0,0,0,3 ; 0,0,0,0 ]
  - d) **eye(4)** yields an identity matrix of size 4x4
  - e) **zeros(3)** yields a matrix of zeros of size 3x3
  - f) **zeros(size(A))** yields a matrix of zeros  
having the same size as A
  - g) **ones(3), ones(2,5), ones(size(A))**  
works the same as zeros() except it produces  
a matrix of ones
  - h) **rand(m,n)** matrix of uniformly distributed  
random numbers of size m by n
  - i) **randn(m,n)** matrix of normally distributed random  
numbers of size m by n
  - j) **linspace(a,b,n)** creates a vector of n elements  
linearly spaced from a to b

- k) `logspace(a,b,n)` creates a vector of n elements logarithmically spaced from  $10^a$  to  $10^b$
- Vectors and matrices can be appended to build larger matrices, e.g. `E=[A,B;C,D]`
  - To disable the echoing results you could include a semicolon after each command line.
  - To check existing list, you could type `who` or `whos`
  - To extract elements:
    - a) `A(1,2)` gives the element at row 1 and column 2
    - b) `A(3,:)` gives the third row of A
    - c) `A(:,4)` gives the fourth column of A
    - d) `A([3,2],[2,1])` extracts rows 3 and 2, and columns 2 and 1
  - To remove rows and columns:
    - a) `A(2,:)=[]` removes the 2<sup>nd</sup> row
    - b) `A(:,1)=[]` removes the 1<sup>st</sup> column
  - Reshaping and vectorization
    - a) `A(:)` yields a vectorized column  
[a<sub>11</sub>; a<sub>21</sub>; ...; a<sub>n1</sub>; ...; a<sub>1n</sub>; ...; a<sub>nn</sub>]
    - b) `reshape(A,m,n)` yields a matrix of size m by n by building it column-wise

## II. Matrix Operations and other operations

- *matrix operations*
  1. addition `C=A+B`
  2. multiplication `C=A*B`
  3. determinant `c=det(A)`
  3. inverse `inv(A)` or `A^(-1)`
  4. right division `C=B/A` (same as `C=B*inv(A)`)
  5. left division `C=A\B` (same as `C=inv(A)*B`)
  6. transpose `C=A.'` (Note: `C=A'` is conjugate transpose)
  7. exponentiation `B=A^3`
  8. matrix exponentiation `B=expm(A)`
  9. rank `R=rank(A)`
  10. eigenvalue/eigenvectors `[Eigenvals,Eigenvecs] = eig(A)`
  11. characteristic polynomial `p = poly(A)`
  - 12 Kronecker product `C=kron(A,B)`
  14. trace `t=trace(A)`
  15. pseudo-inverse `M = pinv(A)`

- *polynomials*
  - 16. roots of polynomial  $\mathbf{R} = \mathbf{roots}([1, 4, 2])$   
( = roots of  $s^2+4s+2=0$  )
  - 17. polynomial, given roots  $\mathbf{p}=\mathbf{poly}([\mathbf{r1},\mathbf{r2}])$
  - 18. polynomial multiplication  $\mathbf{p}=\mathbf{conv}([1, 4, 2],[-2, 3])$   
( =  $(s^2 + 4s + 2)(-2s+3)$  )
- *column-wise operation*
  - 19. column-wise sum  $\mathbf{s}=\mathbf{sum}([1, 2, 3; 4, 5, 6])$   
( = [ 5,7,9] )
  - 20. column-wise product  $\mathbf{p}=\mathbf{prod}([1, 2, 3; 4, 5, 6])$   
( = [ 4, 10, 18] )
- *sorting*
  - 21. sort cols in ascending order  $\mathbf{V} = \mathbf{sort}(\mathbf{A})$   
if  $\mathbf{A} = \begin{bmatrix} 5, & 3 \\ 1, & 4 \end{bmatrix}$  then  $\mathbf{V} = \begin{bmatrix} 1, & 3 \\ 5, & 4 \end{bmatrix}$
  - 22. sorting and getting indices  $[\mathbf{V},\mathbf{K}] = \mathbf{sort}(\mathbf{A})$
- Elementwise operation: precede operator by a dot, e.g.  $\mathbf{A}.\mathbf{*B}$ ,  $\mathbf{A}./\mathbf{B}$ ,  $\mathbf{A}.\mathbf{\wedge}2$

### III. Plotting

- *2D plots*
  - $\mathbf{plot}(\mathbf{x},\mathbf{y})$  uses default
  - $\mathbf{plot}(\mathbf{x},\mathbf{y},\mathbf{x},\mathbf{z})$  combines plot of y vs x and z vs x
  - $\mathbf{plot}(\mathbf{x},\mathbf{y}, '- ', \mathbf{x},\mathbf{z}, '- - ')$  specifies how each plot is drawn:  
solid line for x-y and dashed for x-z
- *Labeling*
  - $\mathbf{xlabel}('Time (sec)')$  labeling the x-axis
  - $\mathbf{ylabel}('Temperature')$  labels the y-axis
  - $\mathbf{title}('Case 1')$  puts title on top of plot
  - $\mathbf{text}(1.2, 3.0, 'Case 1')$  puts text on specified location
  - $\mathbf{gtext}('Case 2')$  text is place with the aid of the mouse

(or use the menu bar in the figure window)

You can use a limited version of TeX formatting for

- greek letters and other symbols (see TeX manual)  
'  $\backslash\mathbf{alpha} \backslash\mathbf{nabla} \mathbf{T}$  ' yields a text :  $\alpha\nabla T$
- subscript and superscripts:  
'  $\mathbf{T}_{\{\mathbf{surround}\}}^{\{\mathbf{a+b}\}}$  ' yields a text :  $T_{\text{surround}}^{a+b}$

- *Axis settings*

<code>axis([0,10,-1,1])</code>	specifies x-range as 0 to 10, and y-range as -1 to 1
<code>axis('square')</code>	makes the plot square
<code>axis</code>	returns to automatic axis mode
<code>hold</code>	freezes the previous plot
- *3D plots*

<code>[x,y]=meshgrid(-10:0.5:10, -2:0.2:2)</code>	initializes x and y matrices
( for the following try <code>z=sin(x/2).*sin(y)</code> )	
<code>mesh(x,y,z)</code>	mesh plot
<code>surf(x,y,z)</code>	surface plot
<code>surfl(x,y,z)</code>	surface plots with lighting
<code>shading interp</code>	smoothens shading scheme as interpolated
<code>colormap(gray)</code>	changes coloring scheme to gray scale
<code>brighten(-0.5)</code>	darkens picture ( if >0 then it brightens)
<code>view([10,60])</code>	changes view to azimuth=10° and elevation=60°

#### IV. Printing

<code>print</code>	sends plot to printer
<code>print h:\sample1.ps</code>	saves the plot as a file
<code>print -deps h:\sample2.eps</code>	specifies format

(or you can use the menu in the figure window)

#### V. Workspaces

<code>clear</code>	erases all variables
<code>clear a, B, Temperature</code>	erases only specified variables
<code>diary h:\case1.dry</code>	saves all terminal activity and saves in file <b>case1.dry</b>
<code>save h:\assign1.mat</code>	saves workspace
<code>save h:\assign1.mat a, B</code>	saves only specified variables
<code>save h:\assign1.mat a, B -ascii</code>	saves in ascii format
<code>load h:\assign1.mat</code>	loads workspace
<code>load h:\data1.any</code>	loads from a file and creates a matrix named <b>data1</b>

( or you can use menu items for importing data and changing paths)

## VI. Some helpful tips

**help**

grabs help information from  
functions or script files

cursor up and down keys

scrolls through previous commands

## VI. Multidimensional Arrays

### a) Creating arrays of higher dimensions

- **Method 1:** set using assignments

Given: **A=[1,2 ; 3,4]**

Then type: **A(:,:,2)= [11, 22; 33, 44]**

- **Method 2:** using cat function

Given: **A=[1,2 ; 3,4]**

**B = [11 , 22; 33, 44]**

Then type: **C=cat(3,A,B)**

- **Method 3:** using “ones”, “zeros” and “repmat”

### b) Dimensions and Reshaping arrays

**ndims(A)**

gets the number of dimensions of A

**size(A)**

gets the size of each dimension of A

**reshape(A,[m,n,p])**

reshapes A into a multidimensional array of size [m,n,p] by first collecting all elements of A in a column and then distributing according to the specified size.

### c) Permuting arrays

**permute(A,[2,1,3])**

(where 1,2,3 are the  
dimensions, not sizes)

changes the dimension indexing,  
this is essentially like the transpose, except  
it applies on any dimension.

## VII. Structures

### Features/Motivation:

- helps encapsulate and organize information of different types
- uses text fields, instead of numeric fields
- can be collected as arrays
- can have subfields
- most commands require the options to come from structures
- most commands can output to structures

### a) Creating Structures

- **Method 1:** Use period to create fields and subfields

```
student.IDNumber=1234;  
student.Name='Hank Hill';
```

- **Method 2:** Use the `struct` command

```
student=struct('IDNumber',1234,...  
              'Name','Hank Hill');
```

- For building structure arrays, just start numbering

```
student(2)=struct('IDNumber',5678,...  
                 'Name','Robert Plant');
```

### b) Extracting Information: just type the structure name including the fields

```
student(2)  
student(2).Name
```

### c) Removing fields

```
student = rmfield( student , 'IDNumber' )
```

## VIII. Cell Arrays

### Features/Motivation

- Cell arrays are similar to structures except you use numeric indices.
- Instead of matrices, cell arrays can have different types of elements

#### a) Creation:

Use assignments with “curly brackets”

```
A = { [1,2;3,4], 'Testing'; {[1,2] ;3}} , 3+5i }
```

#### b) Extracting information:

`A{1,1}` should yield the element in {1,1}  
`A{2,1}{1,1}` assuming element {2,1} is a cell,  
then extracts the {1,1}th element

#### c) Translating to structures and vice versa:

```
C=cell2struct(A(:),...  
    {'matrix','name','vector','cell'})  
D=struct2cell(C);    this converts structure C to cell array  
                    arranged in a column  
E=reshape(D,2,2);    this will reshape cell array D
```

## IX. M-files

### Features/Motivation

- using the Matlab editor or any text editor such as notepad
- to write a user-define function that could take different inputs and yields different outputs
- collect subfunctions together for better organization of files
- several Matlab functions need user-supplied functions in forms of m-files.

a) Example 1. ( simple function )

```
function    y = example1(A,x,b)
%
%    y = example1(A,x,b)
%    =====
%
%    solves for y=Ax+b
%
%
%    (c)2004 Tom Co
%    @ Michigan Technological University
%
%
%    y = A*x + b ;
```

b) Example 2. ( different inputs and outputs)

```
function [y,norm] = example2(A,x,b)
%
%    [y,norm] = example2(A,x,b)
%    =====
%
%    obtains
%    a) y = Ax+b
%    b) or y = Ax if b not included
%    c) norm = sqrt( y' * y )
%
%    y = A*x;
%
%    if nargin==3
%        y = y + b;
%    end
%
%    if nargin == 2, % if norm is required
%        norm=y'*y;
%    end
```



c) Example 3. ( includes subfunctions)

```
function ynorms = example3(Y)
%
%   ynorms = example3(Y)
%   =====
%
%   obtains ynorms = [ ynorm1, ..., ynormn ]
%   where   ynormi= xnorm( y(:,i) )
%           xnorm(x) = sqrt(x'*x)
%
%
%
%   nycols = size(Y,2);
%   ynorms =[];
%   for i = 1:nycols
%       ycol = Y(:,i);
%       ynorms=[ynorms, newnorm(ycol)];
%   end
%
%   function xnorm = newnorm(x);
%       xnorm = sqrt(x'*x);
```